

ADVANCED PLACEMENT PHYSICS B EQUATIONS DEVELOPED FOR 2012

Kinematics  
 FORCE  
 Friction  
 Cent. acceler.  
 TORQUE  
 Momentum  
 Impulse  
 Kinetic E  
 Potential E  
 WORK  
 Power  
 Power  
 Force (SPRING)  
 Potential E (SPRING)  
 PERIOD (SPRING)  
 PERIOD (pendulum)  
 PERIOD  
 FORCE OF Gravitation  
 gravit. Potential energy

NEWTONIAN MECHANICS

|                                    |                                 |
|------------------------------------|---------------------------------|
| $v = v_0 + at$                     | $a =$ acceleration              |
| $x = x_0 + v_0t + \frac{1}{2}at^2$ | $F =$ force                     |
| $v^2 = v_0^2 + 2a(x - x_0)$        | $f =$ frequency                 |
| $\Sigma F = F_{net} = ma$          | $h =$ height                    |
| $F_{fric} \leq \mu N$              | $J =$ impulse                   |
| $a_c = \frac{v^2}{r}$              | $K =$ kinetic energy            |
| $\tau = rF \sin \theta$            | $k =$ spring constant           |
| $p = mv$                           | $\ell =$ length                 |
| $J = F\Delta t = \Delta p$         | $m =$ mass                      |
| $K = \frac{1}{2}mv^2$              | $N =$ normal force              |
| $\Delta U_g = mgh$                 | $P =$ power                     |
| $W = F\Delta r \cos \theta$        | $p =$ momentum                  |
| $P_{avg} = \frac{W}{\Delta t}$     | $r =$ radius or distance        |
| $P = Fv \cos \theta$               | $T =$ period                    |
| $F_s = -kx$                        | $t =$ time                      |
| $U_s = \frac{1}{2}kx^2$            | $U =$ potential energy          |
| $T_s = 2\pi\sqrt{\frac{m}{k}}$     | $v =$ velocity or speed         |
| $T_p = 2\pi\sqrt{\frac{\ell}{g}}$  | $W =$ work done on a system     |
| $T = \frac{1}{f}$                  | $x =$ position                  |
| $F_G = -\frac{Gm_1m_2}{r^2}$       | $\mu =$ coefficient of friction |
| $U_G = -\frac{Gm_1m_2}{r}$         | $\theta =$ angle                |
|                                    | $\tau =$ torque                 |

ELECTRICITY AND MAGNETISM

|   |  |
|---|--|
| $F = \frac{kq_1q_2}{r^2}$ Electric Force  | $A =$ area                                       |
| $E = \frac{F}{q}$ Electric Field  | $B =$ magnetic field                             |
| $U_E = qV = \frac{kq_1q_2}{r}$ Electric Potential Energy                                      | $C =$ capacitance                                |
| $E_{avg} = -\frac{V}{d}$ Electric Field (plates)  | $d =$ distance                                   |
| $V = k\left(\frac{q_1}{r_1} + \frac{q_2}{r_2} + \frac{q_3}{r_3} + \dots\right)$ voltage       | $E =$ electric field                             |
| $C = \frac{Q}{V}$ Capacitance   | $\mathcal{E} =$ emf                              |
| $C = \frac{\epsilon_0 A}{d}$ Capacitance  | $F =$ force                                      |
| $U_c = \frac{1}{2}QV = \frac{1}{2}CV^2$ Potential Energy per capacitance                      | $I =$ current                                    |
| $I_{avg} = \frac{\Delta Q}{\Delta t}$ Current   | $\ell =$ length                                  |
| $R = \frac{\rho \ell}{A}$ Resistance  | $P =$ power                                      |
| $V = IR$ Voltage (Ohm's Law)  | $Q =$ charge                                     |
| $P = IV$ Power  | $q =$ point charge                               |
| $C_p = C_1 + C_2 + C_3 + \dots$ capacitors in parallel  | $R =$ resistance                                 |
| $\frac{1}{C_s} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots$ capacitors in series  | $r =$ distance                                   |
| $R_s = R_1 + R_2 + R_3 + \dots$ resistors in series   | $t =$ time                                       |
| $\frac{1}{R_p} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots$ resistors in parallel | $U =$ potential (stored) energy                  |
| $F_B = qvB \sin \theta$ Magnetic Force (in charge)  | $V =$ electric potential or potential difference |
| $F_B = BI\ell \sin \theta$ Magnetic Force (in wire)   | $v =$ velocity or speed                          |
| $B = \frac{\mu_0 I}{2\pi r}$ Magnetic Field   | $\rho =$ resistivity                             |
| $\phi_m = BA \cos \theta$ Magnetic flux   | $\theta =$ angle                                 |
| $\mathcal{E}_{avg} = -\frac{\Delta \phi_m}{\Delta t}$ emf                                     | $\phi_m =$ magnetic flux                         |
| $\mathcal{E} = B\ell v$ emf for rectangular wire  |  |

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FLUID MECHANICS AND THERMAL PHYSICS

*Density*  
*Hydrostatic pressure*  
*Buoyancy Force*  
*Continuity Equation*  
*Bernoulli's equation*  
*Thermal expansion*  
*Heat transfer*  
*Pressure*  
*Ideal Gas Law*  
*Molecular Kinetic Energy*  
*Speed of a gas molecule*  
*Work done on a system*  
*1st Law of Thermodynamics*  
*Efficiency of heat engine*  
*Efficiency of ideal (Carnot) engine*

$$\rho = m/V$$

$$P = P_0 + \rho gh$$

$$F_{buoy} = \rho Vg$$

$$A_1 v_1 = A_2 v_2$$

$$P + \rho gy + \frac{1}{2} \rho v^2 = \text{const.}$$

$$\Delta \ell = \alpha \ell_0 \Delta T$$

$$H = \frac{kA \Delta T}{L}$$

$$P = \frac{F}{A}$$

$$PV = nRT = Nk_B T$$

$$K_{avg} = \frac{3}{2} k_B T$$

$$v_{rms} = \sqrt{\frac{3RT}{M}} = \sqrt{\frac{3k_B T}{\mu}}$$

$$W = -P \Delta V$$

$$\Delta U = Q + W$$

$$e = \left| \frac{W}{Q_H} \right|$$

$$e_c = \frac{T_H - T_C}{T_H}$$

*Snell's Law*

$A = \text{area}$   
 $e = \text{efficiency}$   
 $F = \text{force}$   
 $h = \text{depth}$   
 $H = \text{rate of heat transfer}$   
 $k = \text{thermal conductivity}$   
 $K_{avg} = \text{average molecular kinetic energy}$   
 $\ell = \text{length}$   
 $L = \text{thickness}$   
 $m = \text{mass}$   
 $M = \text{molar mass}$   
 $n = \text{number of moles}$   
 $N = \text{number of molecules}$   
 $P = \text{pressure}$   
 $Q = \text{heat transferred to a system}$   
 $T = \text{temperature}$   
 $U = \text{internal energy}$   
 $V = \text{volume}$   
 $v = \text{velocity or speed}$   
 $v_{rms} = \text{root-mean-square velocity}$   
 $W = \text{work done on a system}$   
 $y = \text{height}$   
 $\alpha = \text{coefficient of linear expansion}$   
 $\mu = \text{mass of molecule}$   
 $\rho = \text{density}$

ATOMIC AND NUCLEAR PHYSICS

*Energy of a photon*  
*Kinetic energy of photon*  
*de Broglie wavelength*  
*Energy-mass conversion*

$$E = hf = pc$$

$$K_{max} = hf - \phi$$

$$\lambda = \frac{h}{p}$$

$$\Delta E = (\Delta m)c^2$$

$E = \text{energy}$   
 $f = \text{frequency}$   
 $K = \text{kinetic energy}$   
 $m = \text{mass}$   
 $p = \text{momentum}$   
 $\lambda = \text{wavelength}$   
 $\phi = \text{work function}$

WAVES AND OPTICS

*Speed of a wave*  
*index of refraction*  
*CRITICAL ANGLE*  
*LEN/MIRROR equation*  
*Magnification*  
*Location of bright spots*  
*Position of bright spots*

$$v = f\lambda$$

$$n = \frac{c}{v}$$

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

$$\sin \theta_c = \frac{n_2}{n_1}$$

$$\frac{1}{s_i} + \frac{1}{s_o} = \frac{1}{f}$$

$$M = \frac{h_i}{h_o} = -\frac{s_i}{s_o}$$

$$f = \frac{R}{2}$$

$$d \sin \theta = m\lambda$$

$$x_m \approx \frac{m\lambda L}{d}$$

$d = \text{separation}$   
 $f = \text{frequency or focal length}$   
 $h = \text{height}$   
 $L = \text{distance}$   
 $M = \text{magnification}$   
 $m = \text{an integer}$   
 $n = \text{index of refraction}$   
 $R = \text{radius of curvature}$   
 $s = \text{distance}$   
 $v = \text{speed}$   
 $x = \text{position}$   
 $\lambda = \text{wavelength}$   
 $\theta = \text{angle}$

GEOMETRY AND TRIGONOMETRY

*Rectangle*  
*Triangle*  
*Circle*  
*Rectangular Solid*  
*Cylinder*  
*Sphere*

$$A = bh$$

$$A = \frac{1}{2}bh$$

$$A = \pi r^2$$

$$C = 2\pi r$$

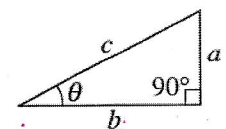
$$V = \ell wh$$

$$V = \pi r^2 \ell$$

$$S = 2\pi r \ell + 2\pi r^2$$

$$V = \frac{4}{3}\pi r^3$$

$$S = 4\pi r^2$$



*Right Triangle*

$$a^2 + b^2 = c^2$$

$$\sin \theta = \frac{a}{c}$$

$$\cos \theta = \frac{b}{c}$$

$$\tan \theta = \frac{a}{b}$$